

B125 GNSS OEM Board



Ultra-compact GNSS Receiver Board

The B125 GNSS OEM board is a compact positioning engine with future-proof signal tracking and scalable positioning from sub-meter DGPS positioning to sub-centimeter RTK positioning.

Low-power consumption and comprehensive communication interfaces, including a high-speed Ethernet port, make the B125 extremely flexible and easy to integrate into any precise positioning application.

- 226 Universal Tracking Channels[™]
- Future-proof tracking of GPS, GLONASS, BeiDou, Galileo, and QZSS
- Low-power consumption
- Precise RTK positioning with data rates up to 100 Hz
- Serial, USB, CAN, and high-speed Ethernet communications
- Hardware-ready for PPP via L-brand satellite downlink or Internet

FEATURES

DION™

Active filter reduces disturbances in positional results, leading to smoother, more consistent output in static and dynamic applications; also allows seamless transition between positioning modes

Multipath mitigation

A proprietary signal-processing algorithm mitigates multipath effect on satellite measurements

Quartz-Lock Loop™ (QLL)

Patented technology eliminates satellite tracking failures and positioning degradation caused by vibration and shock

Ion Shield™

Continuously monitor ionospheric conditions and rapidly switch to iono-free combination if ionospheric disturbances have been detected

Doppler filter

Configure the filter bandwidth to optimize trade-off between noise and dynamic errors, which prevents overshooting velocity output during abrupt changes

Velocity filter

Adaptively reduces noise errors while correcting dynamic errors in raw velocity estimates

HD2

The Topcon determination engine allows use of a pair of boards with a pair of antennas to allow a sub-degree 2D attitude determination

Azimuth filter

Kalman-based filtering to deliver smooth heading even for low-speed single antenna vehicles

A development kit is available to help you rapidly explore and evaluate features and performance of the B125.

Ordering Information: PN 1008510-01 Description: Evaluation board with power supply and communication cables

Complete documentation and design resources are available to reduce your development costs and time as well as minimize design risks and test time. Downloads are available at mytopcon.com.



HEADING

NOITISO



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TRACKING

226 Universal Tracking Channels™
GPS: L1, L2, L2C, L5 GLONASS: L1, L2, L3 Galileo: E1, E5a, E5b, E5AltBOC BeiDou: B1, B2 QZSS: L1, L2, L1C, L1-SAIF, L2C, L5 SBAS: L1 L-Band

Standalone	H: 1.2 m; V: 1.8 m
DGPS	H: 0.3 m; V: 0.5 m
SBAS	H: 0.8 m; V: 1.2 m
RTK	H: 5 mm + 0.5 ppm x baseline; V: 10 mm + 0.8 ppm x baseline
RTK Initialization	Time: < 10 seconds
	Reliability: > 99%
HD2	Heading 0.2°/D, where D is the inter-antenna distance in meters Inclination 0.3°/D, where D is the inter-antenna distance in meters
Velocity	0.02 m/second
Time	30 nsec

ACQUISITION TIME

Hot / Cold Start	< 15 sec / < 44 sec typical
Reacquisition	< 1 sec

COMMUNICATION INTERFACES

RS232	2x ports up to 460.8 kbps
LVTTL UART	1x ports up to 460.8 kbps
USB 2.0 (client)	1x port up to 480 mbps (High Speed)
CAN	1x port (without transceivers), CAN 2.0 A/B , NMEA2000 compliant
Ethernet	1x port supporting TCP/IP, FTP, Ntrip Server/Client

I/OPPS1x output with 5 ns resolution, LVTTL, configurable edge, period, offset, and reference timeEVENT1x input with 5 ns resolution, LVTTL, configurable edge and reference timeDATA AND MEMORYSD card supportIndustrial SLC SD card, 20 Hz writing rate, up to 32GB capacityData Update/Output Rate1 Hz – 100 Hz SelectableData FormatsTPS, RTCM SC104 2.x and 3.x, CMR/CMR+*, BINEXASCII OutputNMEA 0183 versions 2.x, 3.x, and 4.xTemperatureOperating: -40°C to 85°C; Storage: -40°C to 85°C; Storage: -40°C to 85°CVibration95%, non-condensing Survival IEC68-2-27, 11ms, 40g Survival IEC68-2-27, 11ms, 40g Survival IEC68-2-27, 11ms, 75gAcceleration20gPOWER1.4 VDC to 5.5 VDC / 2.0 W typical survival IEC68-2-27, 11ms, 40g Survival IEC68-2-27, 11ms, 40			
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 These specifications will vary depending on the number of satellites used, obstructions, satellite geometry (PDOP), occupation time, multipath effects, and atmospheric conditions. Performance may be degraded in conditions with high ionospheric activity, extreme multipath, or under dense foliage. For maximum system accuracy, always foliow best practices for GNSS data collection.

 CMR/CMR+ is a third-party proprietary format. Use of this format is not recommended and performance cannot be guaranteed. Use of industry standard RTCM 3.x is always recommended for optimal performance.

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